

## CLAIMS

1        1. (currently amended) Apparatus for applying equalization to a complex-valued received  
2        signal, the received signal being single-axis (SA) modulated data, the apparatus comprising:

3              a linear predictive (LPR) filter characterized by a set of real-valued LPR parameters applied to  
4        the received signal, wherein the set of LPR parameters are recursively updated based on one or more  
5        error terms to minimize output power of the LPR-filtered signal;

6              an equalizer configured configurable as either a linear equalizer (LE) or a decision feedback  
7        equalizer (DFE) and applying an estimate of the inverse channel characteristics to the received signal to  
8        generate an equalized signal, wherein:

9                  i) the equalizer comprises a forward (FW) filter characterized by a set of FW filter  
10        parameters, a feedback (FB) filter characterized by a set of real-valued FB filter parameters, and a  
11        decision circuit generating hard decisions for the data of the equalized signal, and

12                  ii) the set of real-valued FB parameters are initialized by the set of real-valued LPR  
13        parameters, the set of FW parameters are initialized with either values of a predetermined impulse  
14        response or values based on a function of a channel response, [[;]] and the set of FW parameters and the  
15        set of FB parameters are recursively updated based on one or more error terms; and

16              an error term calculator configured to generate the one or more error terms from one or more  
17        blind cost criteria based on real-part extraction.

1        2. (currently amended) The invention as recited in claim 1, wherein, for the equalizer:  
2        the FW filter applies a FW function to the received signal to generate the FW-filtered signal;  
3        the FB filter applies a FB function to either soft decisions defined by the equalized signal or the  
4        hard decisions to generate a filtered decision; and

5              a combiner combines the filtered decision with a real-part of the FW-filtered signal to generate a  
6        new soft decision as the equalized signal.

1        3. (currently amended) The invention as recited in claim 2, wherein the decision device  
2        circuit comprises:

3              a slicer configured to generate a symbol from the equalized signal as a hard decision; and  
4              a carrier loop configured to detect and adjust a phase error of the received signal.

1        4. (original) The invention as recited in claim 3, wherein the carrier loop applies the phase  
2        error to de-rotate the signal from the FW filter prior to real-part extraction.

1        5. (original) The invention as recited in claim 3, wherein the carrier loop applies the phase  
2        error to de-rotate the signal applied to the equalizer.

1        6. (currently amended) The invention as recited in claim 3, wherein the equalized received  
2        signal is adjusted, in gain, to generate an unbiased input signal to the slicer.

1        7. (currently amended) The invention as recited in claim 3, wherein the equalized received  
2        signal is scaled with a first scalar prior to its input to the slicer and each hard decision is scaled with a  
3        second scalar prior to its input to the FB filter.

1        8. (original) The invention as recited in claim 7, wherein the first scalar is the reciprocal of  
2        the second scalar.

1           9. (currently amended) The invention as recited in claim 2, wherein the error term  
2       generator calculator receives at least one of the equalized signal and the corresponding hard decision to  
3       generate the one or more error terms.

1           10. (currently amended) The invention as recited in claim 9, wherein the error term  
2       generator calculator also receives the LPR filtered signal.

1           11. (currently amended) The invention as recited in claim 10, wherein the error term  
2       generator calculator generates a single-axis output power (SA-OP) error term.

1           12. (currently amended) The invention as recited in claim 9, wherein the error term  
2       generator calculator generates at least one of a decision directed (DD) error term, a constant modulus  
3       (CM) error term, and a single-axis CM (SA-CM) error term.

1           13. (currently amended) The invention as recited in claim 1, wherein, when operating, the  
2       equalizer is configured in one of at least three modes:

3           a first mode, wherein the set of LPR parameters for the LPR filter are recursively updated based  
4       on a single-axis output power (SA-OP) error term until the set of LPR parameters reach steady-state  
5       values;

6           a second mode, wherein the FW filter, decision circuit, and feedback filter are configured as the  
7       linear equalizer, and the set of FW parameters and the set of FB parameters are adapted based on one or  
8       more error terms based on real-part extraction; and

9           a third mode, wherein the FW filter, decision circuit, and feedback filter are configured as the  
10      DFE, and the set of FW parameters and FB parameters are adapted based on [[the]] a DD error term.

1           14. (original) The invention as recited in claim 13, further comprising an operation  
2       controller, wherein the operation controller either selects the first mode, the second mode, or the third  
3       mode based on a performance measure.

1           15. (original) The invention as recited in claim 14, wherein the performance measure is at  
2       least one of a signal-to-noise ratio, a cluster variance, a frame lock-status, a bit error rate, or an output  
3       power measure for the received signal.

1           16. (currently amended) The invention as recited in claim 13, wherein, in either of the  
2       second mode or the third mode, the set of FW parameters and the set of FB parameters are adapted based  
3       on a combination of [[the]] an SA-CM error term and a decision-directed (DD) error term.

1           17. (currently amended) The invention as recited in claim 1, wherein the FB filter comprises  
2       a multiplexer (mux), a first feedback filter section, and a second feedback filter section, wherein:

3           the first FB filter section applies the set of FB parameters to soft decisions corresponding to the  
4       equalized, received signal;

5           the second FB filter section applies the set of FB parameters to scaled hard decisions generated  
6       by the decision circuit for the equalized, received signal, and

7           the mux either selects as the output of the feedback filter either 1) an output of the first FB filter  
8       section when the equalizer is configured as the LE or 2) an output of the second FB filter section when  
9       the equalizer is configured as the DFE.

1           18. (currently amended) The invention as recited in claim 1, wherein data of the received  
2       signal includes a training sequence, and wherein the apparatus further comprises:

3           a training sequence correlator configured to correlate a conjugated signal from the LPR filter  
4       with a local sequence i) to detect the training sequence and ii) to generate an estimate of the set of FW  
5       filter parameters,

6           wherein the set of FW parameters is initialized based on the correlation.

1           19. (currently amended) The invention as recited in claim 1, wherein the received signal  $r(n)$   
2       is complex-valued, wherein the FW filter is adapted to operate[[s]] in [[the]] a passband and the FB filter  
3       is adapted to operate[[s]] in the at baseband, and wherein the recursive update at time  $n+1$  of at least one  
4       of the sets of FW parameters ( $f_j(n)$ )[[.]] and FB parameters ( $h_j(n)$ ) employs [[the]] a stochastic gradient  
5       descent rule as follows:

$$f_j(n+1) = f_j(n) - \mu r^*(n-j)e_{pb}(n)$$
$$h_j(n+1) = h_j(n) + \mu \varphi(n-j)e_{bb}(n)$$

8       where  $\mu$ ,  $0 < \mu < 1$ , is a step size,  $j$  is a parameter index,  $r(\cdot)$  is the received signal,  $\varphi(\cdot)$  is feedback  
9       regressor data,  $e_{bb}(n)$  is a baseband error term, and  $e_{pb}(n)$  is a passband error term.

1           20. (currently amended) The invention as recited in claim 1, wherein the FW filter is  
2       adapted to operate[[s]] in the at baseband and the FB filter is adapted to operate[[s]] in the at baseband,  
3       and the recursive update at time  $n+1$  of at least one of the sets of FW parameters ( $f_j(n)$ )[[.]] and FB  
4       parameters ( $h_j(n)$ ) employs [[the]] a stochastic gradient descent rule as follows:

$$f_j(n+1) = f_j(n) - \mu r^*(n-j)e_{bb}(n)$$
$$h_j(n+1) = h_j(n) + \mu \varphi(n-j)e_{bb}(n)$$

7       where  $\mu$ ,  $0 < \mu < 1$ , is a step size,  $j$  is a parameter index,  $r(\cdot)$  is the received signal,  $\varphi(\cdot)$  is feedback  
8       regressor data, and  $e_{bb}(n)$  is a baseband error term.

1           21. (currently amended) The invention as recited in claim 1, wherein the received signal is  
2       carrier modulated by data in accordance with a complex vestigial sideband (VSB) format.

1           22. (currently amended) The invention as recited in claim 1, wherein the received signal is a  
2       digital television signal having its data encoded in accordance with an ATSC standard.

1           23. (currently amended) The invention as recited in claim 1, wherein the LPR filter operates  
2       in parallel with the equalizer, wherein the forward filter, feedback filter, and decision circuit are  
3       configured as [[a]] the decision feedback equalizer (DFE), the set of LPR parameters is adapted using an  
4       SA-OPA update rule, and the set of LPR filter parameters  $g_j(n)$  regularize the set of FB filter parameters  
5        $h_j(n)$  by minimization of the criterion  $J_{reg}(h)$  as:

$$J_{reg}(h) = J_{combo}(h) + \lambda \sum_{j=1}^{N_g} |g_j(n) - h_j(n)|^2$$

7       where  $J_{combo}(h)$  is a linear combination of CM and DD cost criteria and the recursive update of the FB  
8       parameters employs an LPR-regularized DFE update rule.

1           24. (currently amended) A method of applying equalization to a complex-valued received  
2 signal, the received signal being single-axis (SA) modulated data, the method comprising the steps of:  
3           (a) applying a linear predictive (LPR) filter characterized by a set of real-valued LPR  
4 parameters to the received signal;  
5           (b) recursively updating the set of LPR parameters based on one or more error terms to  
6 minimize output power of the LPR-filtered signal;  
7           (c) applying either linear equalization (LE) or decision feedback equalization (DFE) to the  
8 received signal to generate an equalized signal, wherein step (c) filters with a forward (FW) filter  
9 characterized by a set of FW filter parameters[[,]] and a feedback (FB) filter characterized by a set of  
10 real-valued FB filter parameters;  
11           (d) generating hard decisions for the data of the equalized signal;  
12           (e) initializing (e1) the set of real-valued FB parameters by the set of real-valued LPR  
13 parameters[[,]] and (e2) the set of FW parameters with either values of a predetermined impulse response  
14 or values based on a function of a channel response;  
15           (f) recursively updating the set of FW parameters and the set of FB parameters based on one  
16 or more error terms; and  
17           (g) generating the one or more error terms from one or more blind cost criteria based on  
18 real-part extraction.

1           25. (original) The invention as recited in claim 24, wherein step (d) generates each hard  
2 decision by the steps of:  
3           (d1) combining i) the real part of the output of the FW filter and ii) the output of the FB filter  
4 to form the equalized signal;  
5           (d2) generating a symbol from the equalized signal as a hard decision; and  
6           (d3) adjusting, by a carrier loop, a phase error of the received signal.

1           26. (original) The invention as recited in claim 25, wherein step (d3) applies the phase error  
2 to de-rotate the signal from the FW filter prior to real-part extraction.

1           27. (original) The invention as recited in claim 25, wherein step (d3) applies the phase error  
2 to de-rotate the signal applied to the equalizer.

1           28. (currently amended) The invention as recited in claim 25, further comprising the step of  
2 adjusting, in gain, the equalized-received signal to generate an unbiased input signal to the slicer.

1           29. (currently amended) The invention as recited in claim 25, comprising the steps of  
2 scaling with a first scalar the equalized received signal prior to its input to the slicer step (d2) and scaling  
3 with a second scalar each hard decision prior to its input to the FB filter.

1           30. (original) The invention as recited in claim 29, wherein the first scalar is the reciprocal  
2 of the second scalar.

1           31. (currently amended) The invention as recited in claim 24, wherein, for step (c),  
2 equalization occurs in one of at least three modes:  
3           a first mode, wherein the set of LPR parameters for the LPR filter are recursively updated based  
4 on a single-axis output power (SA-OP) error term until the set of LPR parameters reach steady-state  
5 values;  
6           a second mode, wherein the FW filter, a decision circuit, and the feedback filter are configured as  
7 the linear equalizer for LE, and the set of FW parameters and the set of FB parameters are adapted with  
8 one or more error terms based on real-part extraction; and

9           a third mode, wherein the FW filter, decision circuit, and feedback filter are configured as the ~~for~~  
10          DFE, and the set of FW parameters and the set of FB parameters are adapted based on a DD error term.

1           32. (currently amended) The invention as recited in claim 31, wherein, in either of the  
2          second mode or the third mode, the set of FW parameters and the set of FB parameters are adapted based  
3          on a combination of an SA-CM error term and [[the]] a decision-directed (DD) error term.

1           33. (currently amended) The invention as recited in claim 24, for step (f), recursive update  
2          at time  $n+1$  of at least one of the sets of FW parameters ( $f_j(n)$ )[[,]] and FB parameters ( $h_j(n)$ ) employs  
3          [[the]] a stochastic gradient descent rule as follows:

$$4 \quad f_j(n+1) = f_j(n) - \mu r^*(n-j)e_{pb}(n)$$
$$5 \quad h_j(n+1) = h_j(n) + \mu \varphi(n-j)e_{bb}(n)$$

6          where  $\mu$ ,  $0 < \mu < 1$ , is a step size,  $j$  is a parameter index,  $r(\cdot)$  is the received signal,  $\varphi(\cdot)$  is feedback  
7          regressor data,  $r(n)$  is the received signal,  $e_{bb}(n)$  is a baseband error term, and  $e_{pb}(n)$  is a passband error  
8          term, wherein the FW filter operates in [[the]] a passband and the FB filter operates in the ~~at~~ baseband.

1           34. (currently amended) The invention as recited in claim 24 wherein, for step (f), recursive  
2          update at time  $n+1$  of at least one of the sets of FW parameters ( $f_j(n)$ )[[,]] and FB parameters ( $h_j(n)$ )  
3          employs [[the]] a stochastic gradient descent rule as follows:

$$4 \quad f_j(n+1) = f_j(n) - \mu r^*(n-j)e_{bb}(n)$$
$$5 \quad h_j(n+1) = h_j(n) + \mu \varphi(n-j)e_{bb}(n)$$

6          where  $\mu$ ,  $0 < \mu < 1$ , is a step size,  $j$  is a parameter index,  $r(\cdot)$  is the received signal,  $\varphi(\cdot)$  is feedback  
7          regressor data,  $r(n)$  is the received signal, and  $e_{bb}(n)$  is a baseband error term, wherein the FW filter  
8          operates in the ~~at~~ baseband and the FB filter operates in the ~~at~~ baseband.

1           35. (currently amended) The invention as recited in claim 24, wherein, for step (f), recursive  
2          update of the set of LPR filter parameters ( $g(z)$ )  $g_j(n)$  uses an SA-OPA update rule and the set of FB filter  
3          parameters ( $h(z)$ )  $h_j(n)$  for the DFE employs an LPR-regularized DFE update rule for [[the]] minimization  
4          of criterion  $J_{reg}(h)$  as:

$$5 \quad J_{reg}(h) = J_{combo}(h) + \lambda \sum_{j=1}^{N_g} |g_j(n) - h_j(n)|^2$$

6          where  $J_{combo}(h)$  is a linear combination of CM and DD cost criteria.

1           36. (currently amended) The invention as recited in claim 24, wherein, ~~for step a)~~,  
2          single-axis modulated the received signal is [[the]] carrier modulated by [[the]] data in accordance with a  
3          vestigial sideband (VSB) format.

1           37. (currently amended) The invention as recited in claim 24, wherein, ~~for step a)~~, the  
2          single-axis modulated the received signal is a digital television signal having its data encoded in  
3          accordance with an ATSC standard.

1           38. (currently amended) The invention as recited in claim 24, wherein data of the received  
2 signal includes a training sequence, and wherein step (e2) comprises the steps of:  
3           (e2i) correlating a conjugated signal from the LPR filter with a local sequence;  
4           (e2ii) detecting the training sequence; and  
5           (e2iii) generating an estimate for the set of FW ~~filter~~ parameters based on the correlation of step  
6 (e2i).